ROSETTA

FLIGHT REPORTS of RPC-MAG

RO-IGEP-TR-0015

Issue: 1 Revision: 2

August 3, 2005

Anomaly Report & Analysis

of the

MAG-OB Failure in June 2005

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1 Introduction

This Analysis Report is related to the Anomaly Report ROS–SC–91 :

Cesa Anomaly Report Tracking System

Contraction of the second second	Rosetta	Spacecraft Anoma	alies			Project ID	ROS_SC
SC	MAG se	ensor not working		State	Open	ID	ROS_SC-91
Originate	or	Armelle Hubault	Criticality	Low			
Created		2005-06-21 15:07	Urgency	Low	Event Type	Unexpecte r	ed_Event/Behavior
			Reproducibility	Unknown	Туре	Local	
Occurre	nce Date	2005-06-17	Classification	Space Segment Payload RPC	1		
Descript	ion						
Descript	ion	During RPC ac	tivities on DOY 20	05.167, MAG tear	n reported a prol	olem with one	e of MAG sensors.
			s that the sensor di switch on at 167:0				6 to 19 June); it
		A power cycle	was subsequently	requested on DO	Y 172 and this so	lved the proj	blem
		and the market for the second	temperature on DC	all strange and some on some of		and the second second second	
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Figure 1: Anomaly Report: AR-ROS-91

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2 Event description

Studies about cometary orbits revealed the unique chance to meet the tail of the just recently discovered comet P/CATALINA. Our Swedish colleagues from the RPC–LAP team computed, that ROSETTA would pass CATALINA's plasma tail at a distance of just 10 Million kilometers in the time period June 17. - 19., 2005. Therefore, it was decided to switch on RPC on July 16. and perform measurements until June 19.

On the first view everything looked nominal. According to our HK data all necessary voltages had the right values (refer to the plots in Appendix B) and the RPC-MAG IB sensor transmitted reasonable data in the usual manner (refer to Figure 2). The OB sensor, however, sent a faulty signal (refer to Figure 3):

- the B_x component was permanently saturated.
- the B_u component showed erratic variations of a few thousand Nanotesla.
- the B_z component was permanently saturated.

This behavior did not change over the whole operation period until the switch off on June 19. The OB data looked erroneous in the science packets (sampled by 3 individual 20 bit ADCs) and the housekeeping packets (sampled by a different 16 bit ADC) as well (refer to Appendix C). The temperature of the IB and OB sensor (thermistors inside the magnetic field sensors) was, however, measured in the right way (refer to Figure 17).

As only the OB sensor failed and the other parts of the instrument were working nominally, we could be quite sure that there was at no time any danger for the other RPC-Instruments or the spacecraft. Therefore, RPC stayed powered on until the evening of June 19 (ROSETTA was out of pass anyway) and was switched off via MTL at 2005-06-19T23:15.

The next switch on was executed manually at 2005-06-21T08:02. Now everything was nominal as usual. The complete instrument, both sensors, worked fine as all the time before.

RPC was finally switched off manually at 2005-06-21T16:29.

Remark:

The increased noise level of the IB sensor is caused by the variations of the OB–Y sensor with an amplitude of some thousand Nanotesla. Both sensors are only 15 cm apart. Therefore, the huge OB–Y variations have a magnetically influence to the IB sensor in the order of some Nanotesla.

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2.1 Diagnosis

There were detailed discussions inside the MAG team about the erroneous behavior. The first guess was that there might occur problems due to the low sensor temperature. Studying our instrument development description, however, revealed, that the sensors have been operated (several power on/off cycles) down to at least -160° C during the development phase (refer to the test description in the RFW sheet, Appendix G). Therefore, a temperature effect was discarded as error source. An in depth analysis, excluding the nominal working instrument parts step by step, should help to locate the origin of the error:

- RPC was powered on nominally in terms of stable voltages.
- All necessary voltages (+5V, -5V, U_{ref} =2.5V) were present as expected ¹ (proofed by HK data, refer to Appendix B).
- Data were transmitted in HK and Science frames.
- The Thermistors inside the OB and IB sensors worked properly.
- The IB sensor worked nominally.
- OB science and OB HK values showed the same signature.
- The overall RPC current was nominal (refer to the Figures in Appendix D)
- Readings are constant but not zero. Therefore, a loose contact in the connectors or harness can be screened out.
- The failure must be originated somewhere in the OB part of the instrument rather than in any commonly used section.

Due to this facts the only possible error source seems to be:

• Excitation of OB missing or faulty.

With this assumption the error source can be encircled a bit more:

• Oscillator failure.

 \sim Not possible, as RPC-MAG is operating with only one master oscillator working on $f_0 = 4.19443$ MHz.

All frequencies needed for the whole instrument are derived from this oscillator. As the s/w runs properly, the FPGAs must work properly as well (the FPGAs need the master clock!): f_0 signal is obviously present.

 $^{^{1}}$ However, there can not be made any statement about transient switch on events, as the HK sampling rate is only 1 frame per 32 s. For such an analysis we would need an oscilloscope access to the RPC unit....

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- The master clock f_0 is divided by 84 to generate an input frequency of $f_1 = 50$ kHz for the FGM drive electronics (refer to circuit diagram in Appendix E). Furthermore this frequency is divided by 2 times 2 to provide the needed $f_2=25$ kHz and $f_3=12.5$ kHz. Thus, up to this point the failure probability is extremely low.
- The most likely failure source is the complex behavior of the resonant circuit consisting of L_1 , C_s and the sensor excitation coil (refer to the right side of Figure 16) during the power on phase.

Rationale:

The described resonant circuit has to oscillate exactly on his resonance frequency of 12.5 KHz. This can only be guaranteed, if during the RPCMAG activation phase enough power is provided via the s/c or RPC PIU power supply. It is absolutely necessary that the supply voltage rises "immediately" with a steep flank. If the flank is to flat, respective the slew rate is to slow, the resonant circuit is not able to draw the high initial current needed to fall into the right oscillation state (the resonant circuit is not excited with a simple sinusoidal signal but with steep needle pulses to minimize power consumption. Therefore, sufficient power has to be provided to generate even the first needle pulse in the right height). It might happen that the circuit will not start oscillating which will of course cause a failure behavior.

This behavior is a known fact from the development time of the instrument and has also been reproduced recently with a RPCMAG prototype unit at IGEP TU-BS using a "soft" power supply. The failure did, however, not occur if the supply voltages were switched on and connected instantaneously using a relais.

The observed failure never happened during s/c ground tests or in flight (until now) with the original s/c power units. Maybe the instrument was switched on in an inconvenient moment, when there were spikes on the main power lines or the s/c power consumption was to high for a very short time. Therefore, we had a look to the total drawn current by RPC (refer to Appendix D). These figures, however, do not show any abnormal behavior. But the time resolution (1 Minute) and also the current resolution is not high enough to reveal transient start-up events.

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3 Conclusion

The observed failure in June, 2005 did not leave any damage behind. All RPC is again working nominal.

The failure source can not be located definitely, but with the utmost probability, a catenation of unfortunate circumstances lead through a faulty oscillation of the resonant circuit in the sensor excitation drive. This is an absolutely uncritical error which can be corrected by a repeated Power off/on cycle.

The best modus operandi for RPCMAG would of course be to switch the instrument on, ensure that it works nominally, and leave it in the powered state to minimize the power on cycles.

A Plots of the IB and OB Sensors - Science Data

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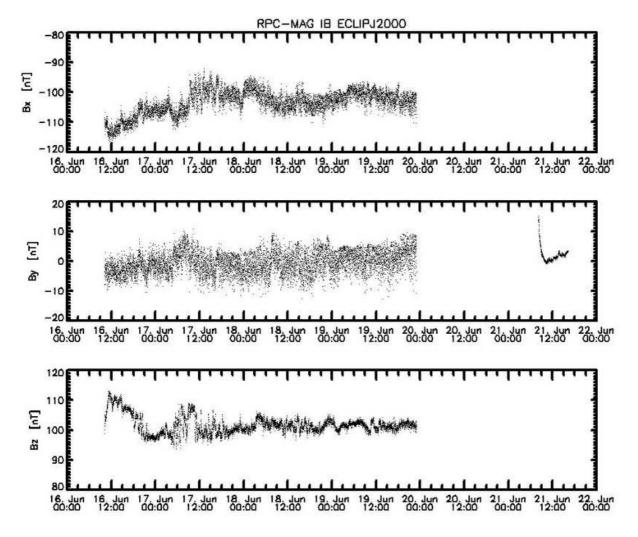
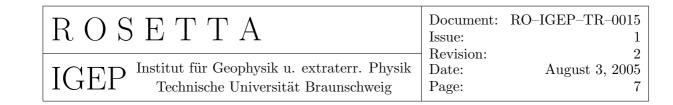


Figure 2: RPCMAG: Magnetic field measured with the IB Sensor



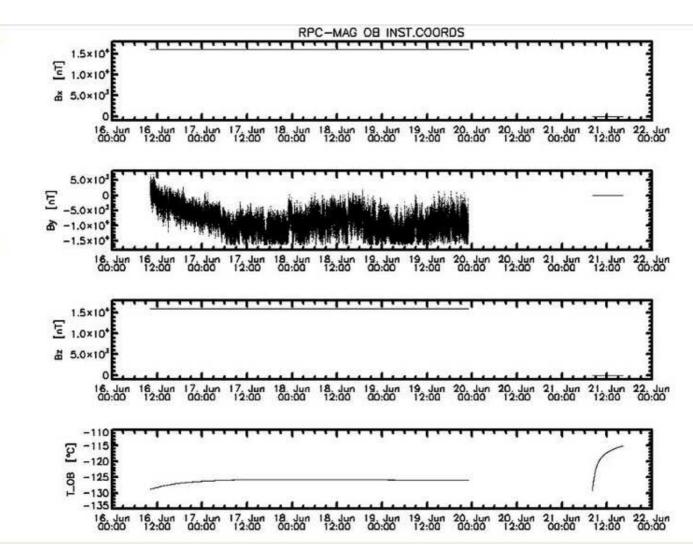
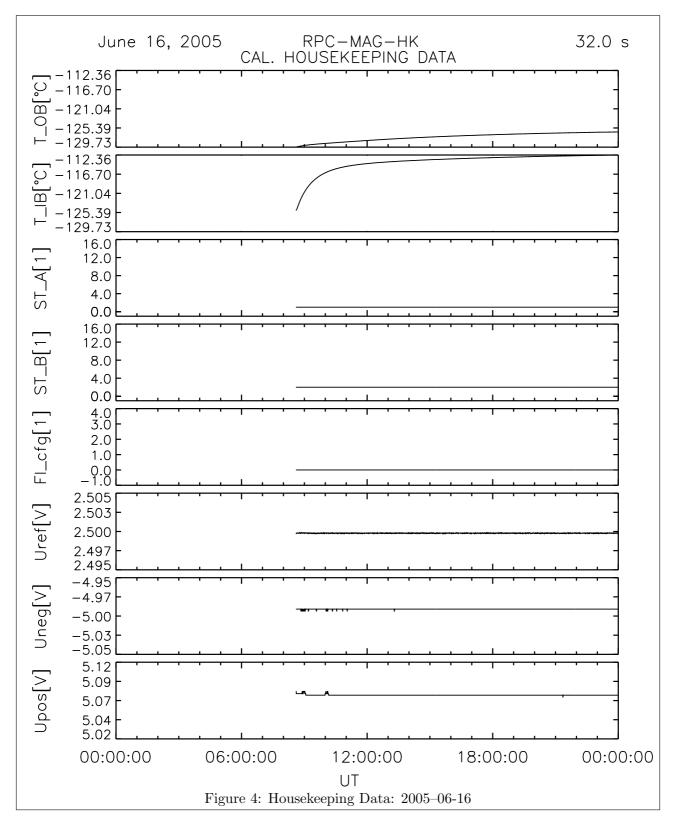
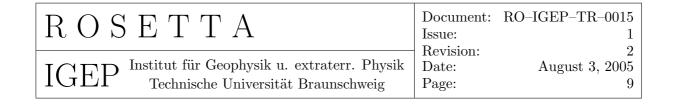


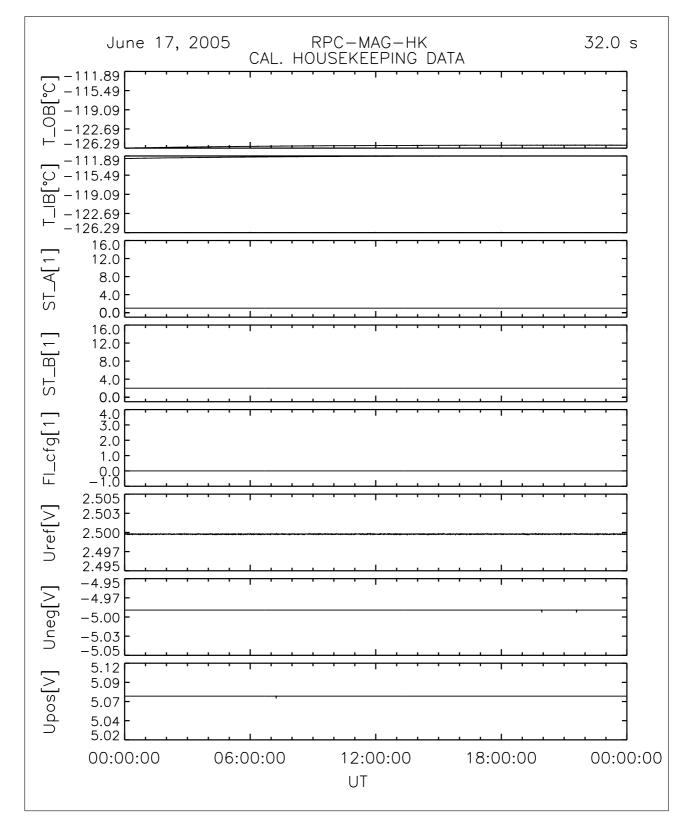
Figure 3: RPCMAG: Magnetic field measured with the OB Sensor

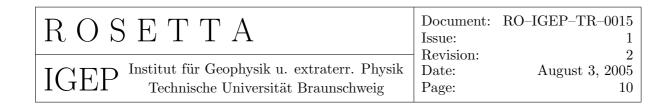
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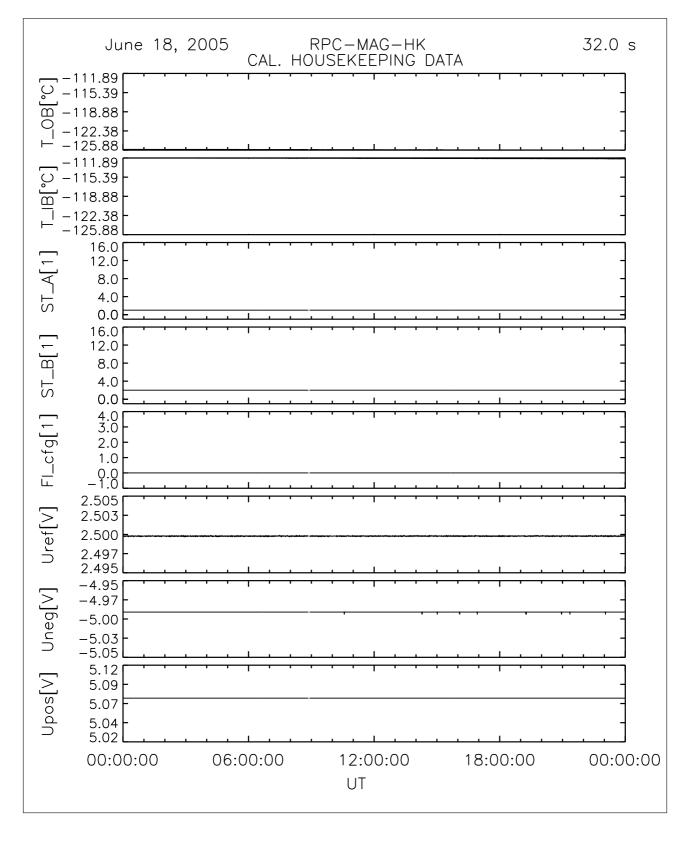
B Plots of the Housekeeping Data

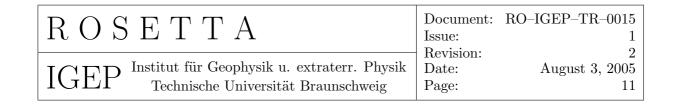


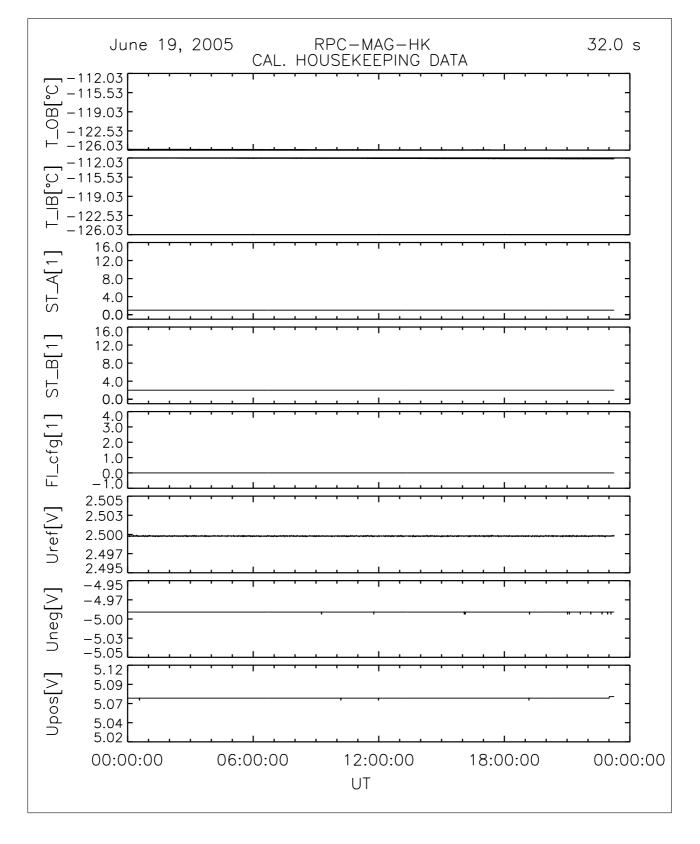


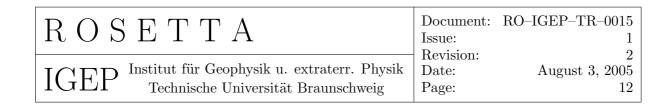


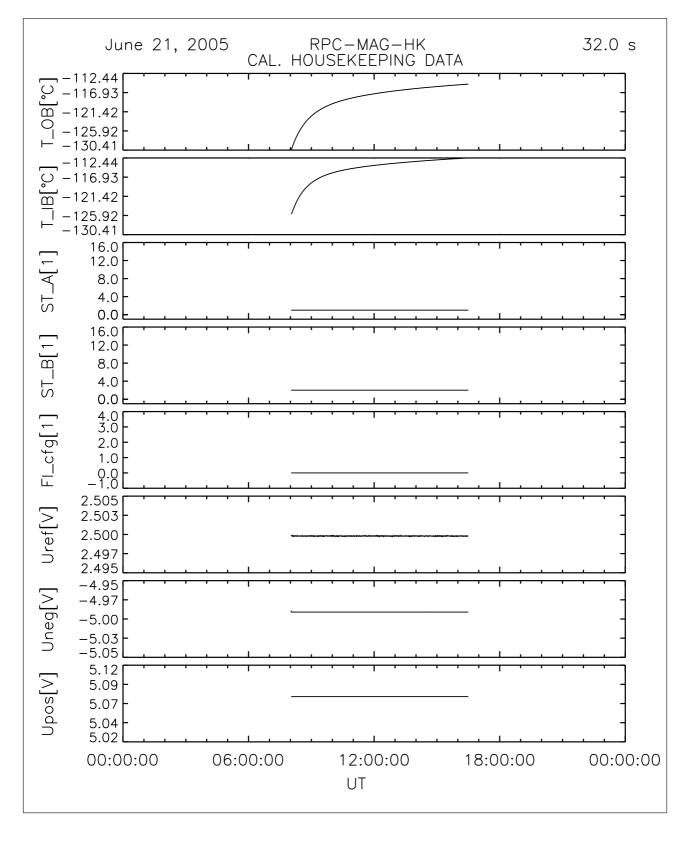






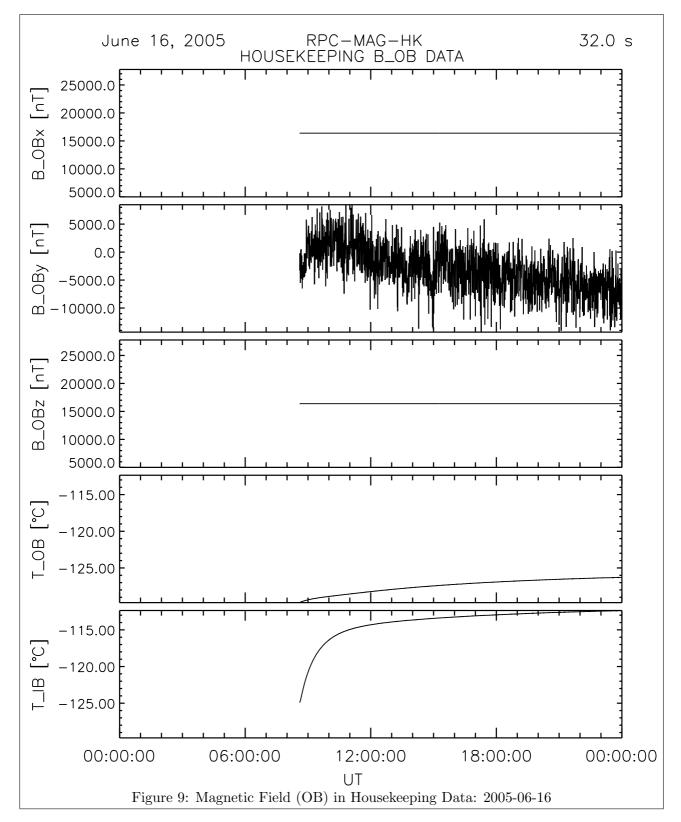


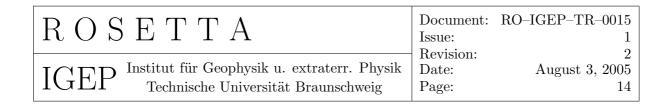




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C Magnetic Field (OB–Sensor) inside the HK Data





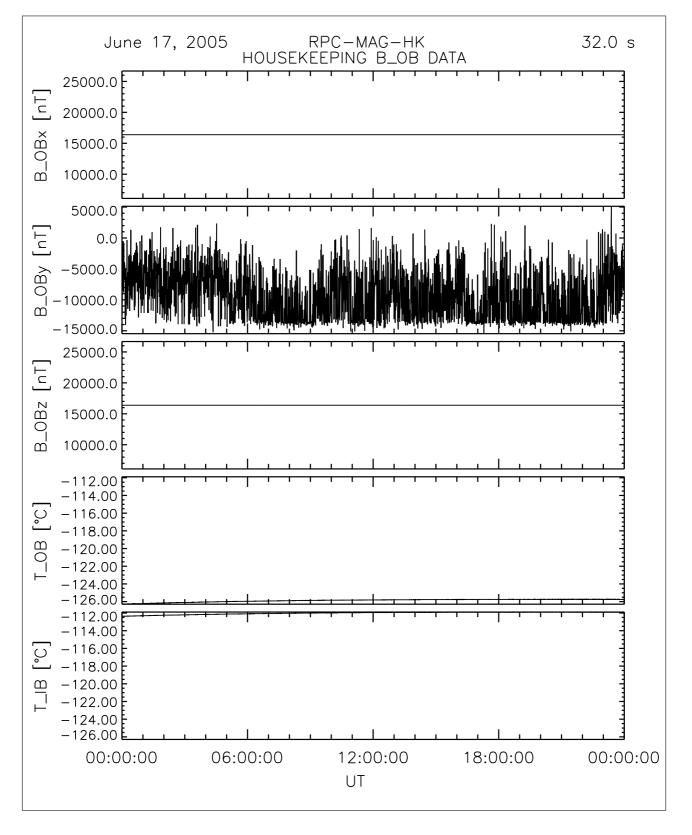


Figure 10: Magnetic Field (OB) in Housekeeping Data: 2005-06-17

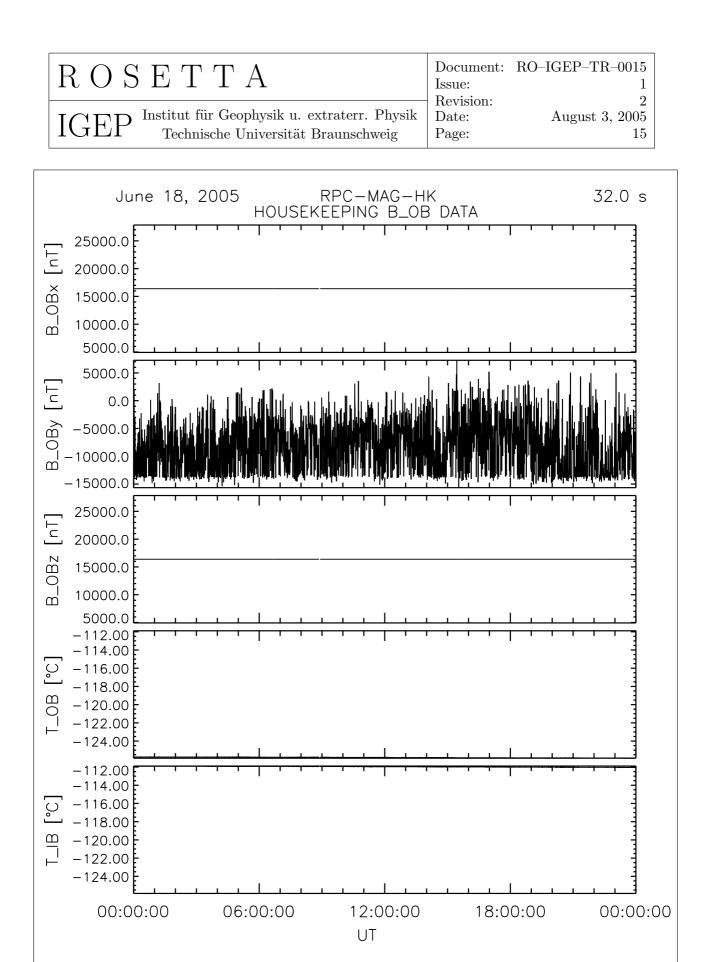
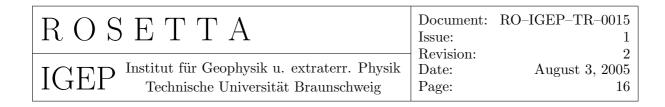


Figure 11: Magnetic Field (OB) in Housekeeping Data: 2005-06-18



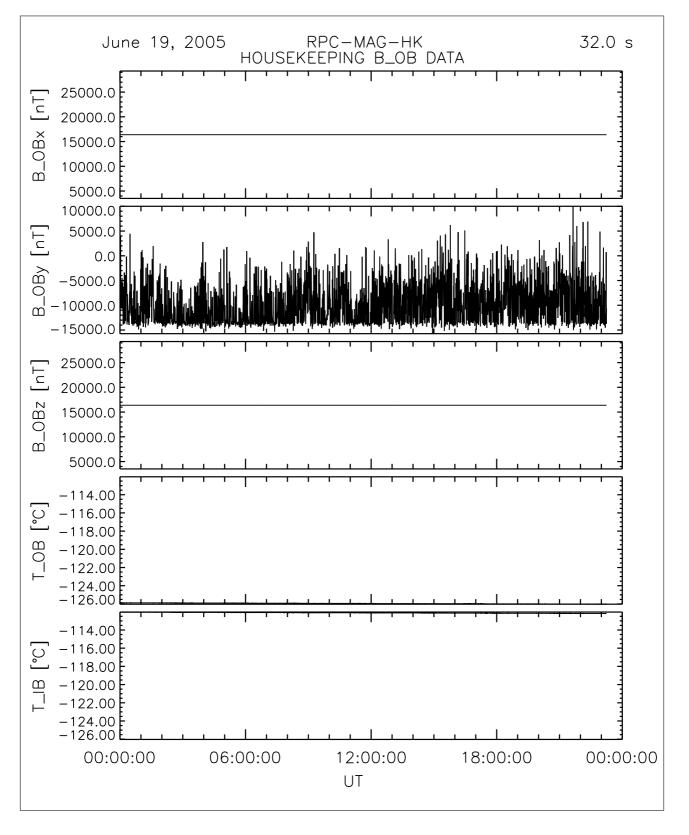
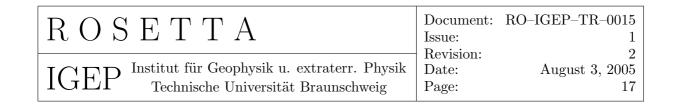
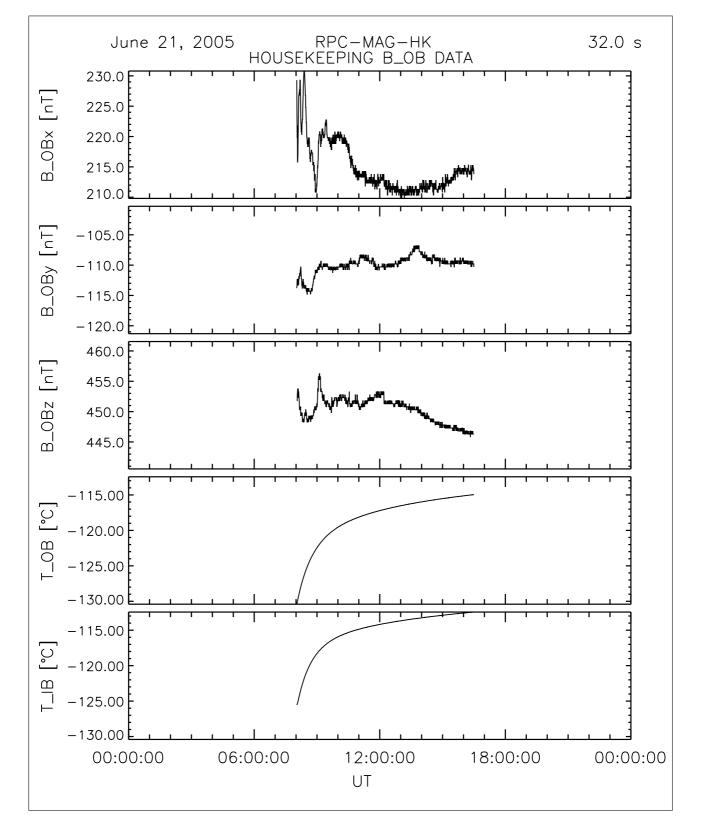


Figure 12: Magnetic Field (OB) in Housekeeping Data: 2005-06-19





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D PLOTS of the Total RPC Current

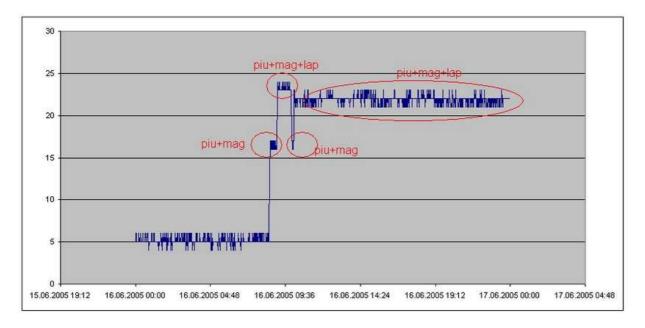


Figure 14: RPC: Total Current (in relative units): 2005-06-16

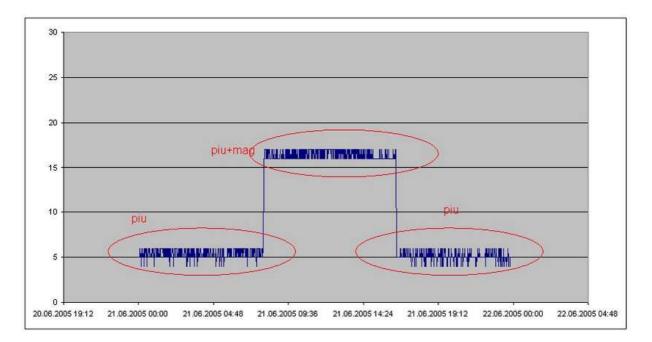


Figure 15: RPC: Total Current (in relative units): 2005-06-21

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E The RPCMAG FGM Driver Electronics

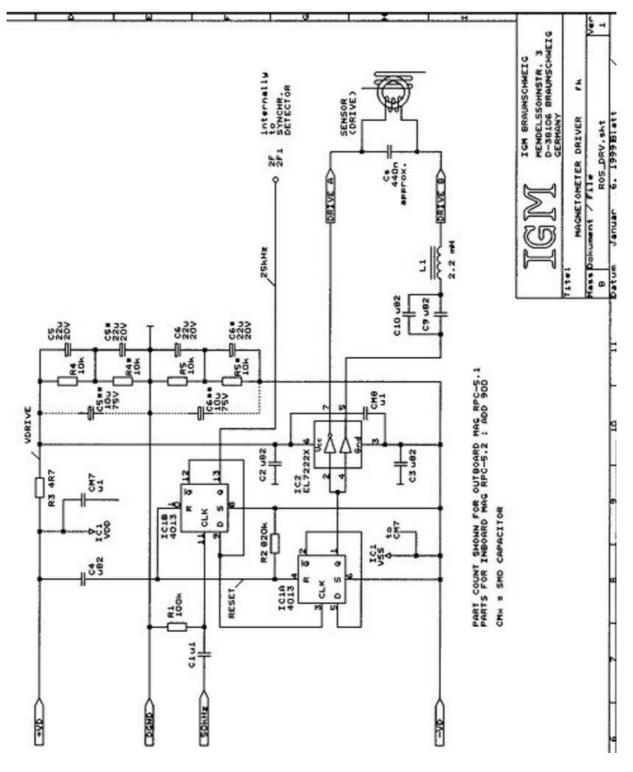


Figure 16: RPCMAG Driver Electronics

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F The Sensor Temperatures and s/c Attitude during the Period June, 16.-21.

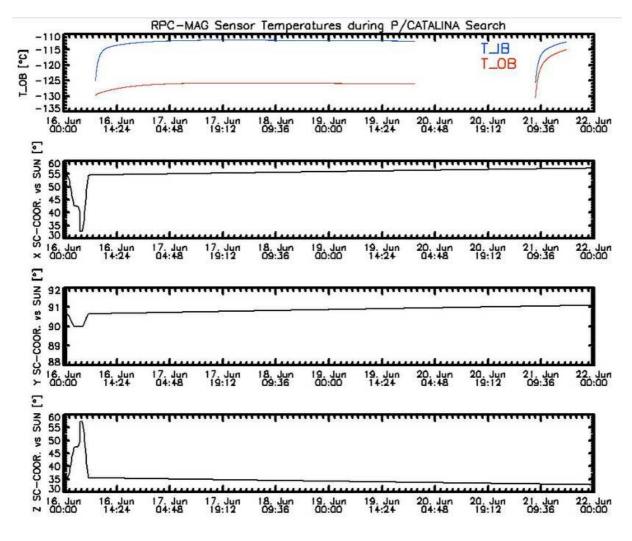


Figure 17: RPCMAG: Sensor Temperatures

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G RFW for Thermal Tests

	REQUEST FOR WAIVER		[0] RFW number:		RO-RPC-RW		A CAL
Rosetta Plasma Consortium		Issue/Rev: 01/00		Date: 03 /		/01 /2001	
Equipment: () 1: IES () 2: ICA () 3:	LAP ()4	: MIP (x) 5:	MAG () 6: PIU	() 7: EGSE	() 8: othe
Unit:	Model:	() BB	() STM	(x)		(x) FM	(x) FS
Related NCR (if any):							
[1] Title of Request:							
Modified Thermal Vacuum	Test Procedure f	or RPC-MAC	3 Sensors 5.1	,5.2 Qua	lification	and Acceptan	ce Test
[2] Affected End Items: RPC-MAG Sensors –5.1,-5	2						
[3] Requirements / Interfac EID –A sect.4.4.10	e Documents affe	cted:					
[4] Description of Deviatio	<i>n</i> :						
and down to -160C in a T-range. 2. We were unable to perf to - 160C.We only cou [5] Other items or requirem	orm 8 cycles (Qu ld run 2 ½ cycles	alification) a because of f	nd 4 cycles (Acceptar	ce) from	room temperat	ture
none							
[6] Need for RFW / Rational To control the proper oper magnetic environment .Bec thermistor no vacuum is rec have thrown the sensors into	ation of the MAC ause also the very puired. To test the o liquid nitrogen	3 sensors dur 7 small sensor 9 maximum n as a maximu	rs(36g) conta nechanical str	ain only r esses cau	nechanica sed by ne	al parts besides	olled
Acceptance test we then per requested was – 160Conly at minimum temperatures. V The total number of cycles	for Qual)respect We also performe was limited becau	ively down to d several swi 1se of liquid 1	between roor o -160C for 6 tch-ON/Off s nitrogen avai	n tempera 5! Sensors sequences lable (40	- no failu ature and s (FM,FS s. All tests Oliter liqu	re). For qualifi down to – 192 S,FSS) with ab- s went fine, no id nitrogen we	atures we cation and C (out 4 hours failure. ere
Acceptance test we then per requested was -160 Conly at minimum temperatures. We the total number of cycles consumed for these 2 1/2 c	for Qual)respect We also performe was limited becau	ively down to d several swi 1se of liquid 1	between roor o -160C for 6 tch-ON/Off s nitrogen avai	n tempera 5! Sensors sequences lable (40	- no failur ature and s (FM,FS a. All tests Oliter liquer in Euro	re). For qualifi down to – 192 S,FSS) with ab- s went fine, no id nitrogen we	atures we cation and C (out 4 hours failure. ere
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Figure 18: Request for Waiver: Thermal Tests